

ANPz101eXT12/NUM(+)

closed loop, linear, vertical stepper positioner with optoelectronic encoder and extended travel range

Technical Specifications

Technology		Compatibility with Electronics	
travel mechanism	inertial piezo drive	ANC350 piezo positioning controller	ANC350/NUM
Size and Dimensions		Working Conditions	
footprint; height	24 x 24; 32 mm	mounting orientation	axis vertical
maximum size	24 x 24; 44 mm	magnetic field range	0 .. 7 T
weight	80 g	temperature range (/RT, /HV, /UHV)	0 .. 100 °C
Coarse Positioning Mode		max. bake out temperature (/UHV, /LT/UHV)	150 °C
@ 300 K		minimum pressure (/RT)	1E-4 mbar
input voltage range	0 .. 60 V	minimum pressure (/HV)	1E-8 mbar
typical actuator capacitance	1.60 µF	minimum pressure (/UHV)	5E-11 mbar
travel range (step mode)	12 mm	Position Encoder	
typical minimum step size	50 nm	readout mechanism	optoelectronic sensor: /NUM & /NUM+/(U)HV
maximum drive velocity	≈ 3 mm/s	sensor power (when measuring)	300 mW
Fine Positioning Mode		encoded travel range	full travel
@ 300 K		wavelength of illumination	870 nm
input voltage range	0 .. 100 V	sensor resolution	10 nm
fine positioning range	0 .. 7.5 µm	repeatability	150 nm
fine positioning resolution	sub-nm	linearity (over full travel)	< 0.01 %
Materials (non-magnetic)		absolute accuracy	< 0.1 % of travel range
positioner body	titanium (upgrade option: copper beryllium)	Connectors and Feedthroughs	
actuator	PZT ceramics	/RT Versions	all /HV, /UHV Versions
connecting wires	insulated twisted pair, copper	connector type	14-pole connector
Load (@ ambient conditions)		electrical feedthrough solution	---
mounting orientation: axis vertical			
maximum load	2 N (200 g)		
maximum dynamic force along the axis	5 N		
Mounting			
from the top	2 through holes dia 2.2 mm, cntrbr. f. M2		
from the bottom	2 threads M2.5 x 3.4 mm		
load on top	10 threads M2 x 3.3 mm		
Article Numbers			
/RT version	1005152		
/HV version	#		
/UHV version	#		

Technical Drawings

